

# Support Vector Machine (SVM)

A log-barrier approach

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Convex optimization and applications

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## Convex optimization

$$\min_{x \in D} f(x) \quad (1)$$

where  $f(x)$  and  $D$  are convex.

## Quadratic program

$$\min_{Ax \leq b} x^T P x \quad (2)$$

where  $P \succeq 0$  for a convex program.

# Log barrier method

## Aim

To make inequality constraint implicit in the objective function.

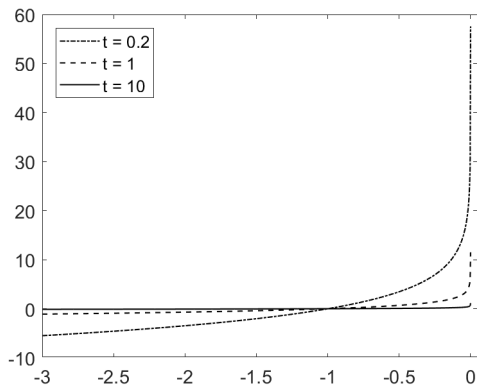
## Indicator function

$$I_-(u) = \begin{cases} 0; & u \leq 0 \\ \infty; & u > 0 \end{cases} \quad (3)$$

## Approximate indicator function (Log barrier function)

$$\hat{I}_-(u) = -(1/t)\log(-u) \quad (4)$$
$$\text{dom}(\hat{I}_-) = -\mathbb{R}_{++}$$

# Approximate log barrier function



**Figure 1:** Log barrier function for  $t = 0.2, 1, 10$

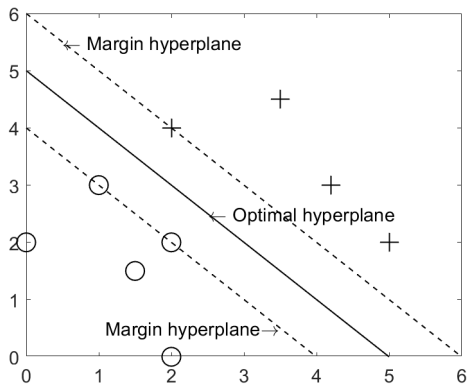
# Support Vector Machine

Given a set of linearly separable data points, find a separating hyperplane that maximizes the margin between itself and the nearest data points.

## (Definition) Margin

Twice of minimum distance between the separating hyperplane and data points.

# Support Vector Machine



**Figure 2:** Separating hyperplane for linearly separable data points

# Cost function for SVM

Given a set of linearly separable data points and labels  $(x_i, y_i)$ , finding the maximum margin separating hyperplane is equivalent to the constrained problem:

## Quadratic program for SVM

$$\begin{aligned} \min_{w,b} & \|w\|^2 \\ \text{s.t. } & y_i(\langle w, x_i \rangle + b) \geq 1, \quad \forall i \end{aligned} \quad (5)$$

where  $\langle w, x \rangle + b = 0$  is the equation of hyperplane (decision boundary).

# SVM using log-barrier method

## Quadratic program for SVM

$$\begin{aligned} \min_{w,b} & \|w\|^2 \\ \text{s.t. } & y_i(\langle w, x_i \rangle + b) \geq 1, \forall i \end{aligned} \quad (6)$$

## Optimization problem using log barrier method

$$\min_{w,b} \left[ \|w\|^2 - (1/t) \sum_i \log(-1 + y_i(\langle w, x_i \rangle + b)) \right] \quad (7)$$

*where*  $t \in \mathbb{R}_+$



# Feasible start point

- ▶ Presence of logarithm in objective function restricts start of optimization from any random initial point
- ▶ Need for additional mechanism to find a feasible starting point

## Optimization problem for a feasible start point

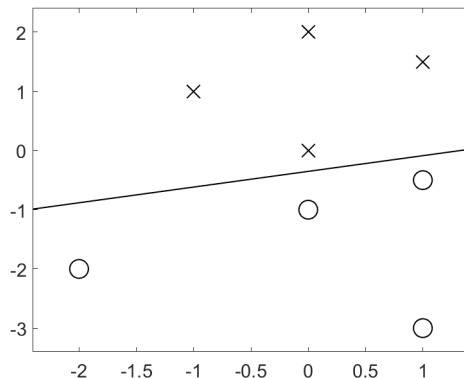
$$\begin{aligned} & \min_{w,b,s} s \\ & \text{s.t. } (1 - y_i(\langle w, x_i \rangle + b)) \leq s; \forall i \end{aligned} \quad (8)$$

- ▶ Can put a lower bound on  $s$  to prevent unnecessary computation

# Algorithm

- ▶ Fetch the dataset
- ▶ Identify a feasible starting point for SVM model (using a log barrier method) (7) using (8)
- ▶ Run the optimization problem (7) with the obtained starting point

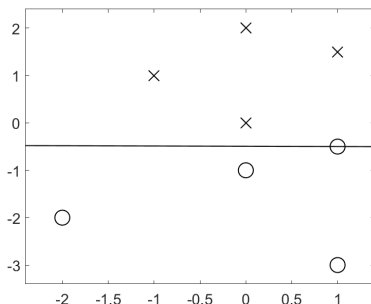
# Result



**Figure 3:** Separating hyperplane for a linearly separable 2D dataset using log barrier method ( $t = 1$ )

# Result

Difficult to minimize the optimization problem (7) for large value of  $t$  in one step since its Hessian varies rapidly near the boundary of the feasible set.



**Figure 4:** Separating hyperplane for a linearly separable 2D dataset using log barrier method ( $t = 10$ )

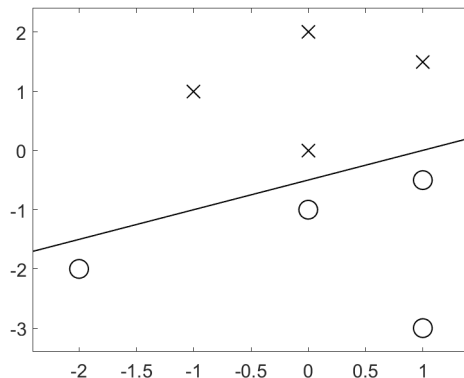
## (Defintion) Central path

Let  $x^*(t)$ ,  $t > 0$  be the solution of

$$\begin{aligned} \min t(f_0(x)) + \phi(x) \\ \text{s.t. } Ax = b \end{aligned} \tag{9}$$

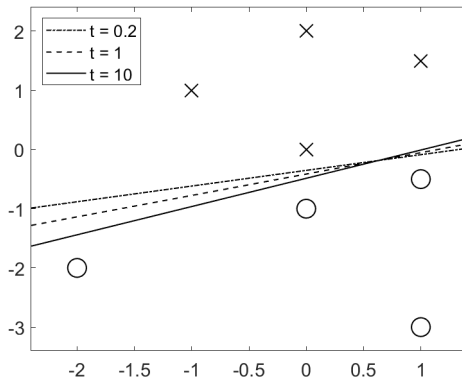
Then the central path associated with it is defined as the set of points  $x^*(t)$ ,  $t > 0$  which we call the set central points.

# Result



**Figure 5:** Separating hyperplane for a linearly separable 2D dataset using log barrier method ( $t = 10$ ) by incorporating the concept of central path

# Result

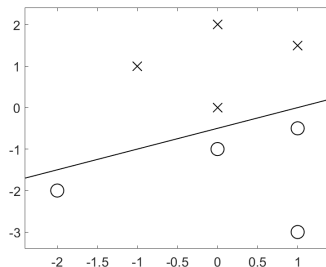


**Figure 6:** Central path of separating hyperplane ( $t = 0.2, 1, 10$ ) for a linearly separable dataset

# Comparison

## Exact method

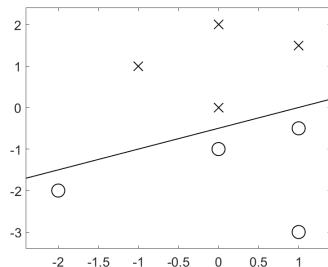
$$\begin{bmatrix} -1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + 1 = 0$$



**Figure 7:** SVM using exact method

## Log barrier method

$$\begin{bmatrix} -1.0024 & 2.0994 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + 1.0204 = 0$$

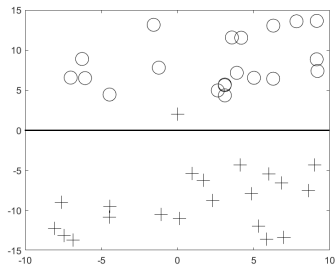


**Figure 8:** SVM using log barrier method and central path ( $t = 10$ )

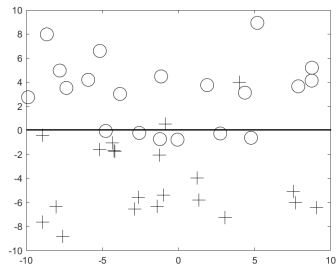


# Soft margin SVM (Motivation)

When a dataset is not linearly separable due to insufficient features, noise and spurious data.



**Figure 9:** Soft margin to increase margin



**Figure 10:** Soft margin to handle linearly inseparable dataset

## Soft margin SVM classification

$$\begin{aligned} \min_{\substack{w, b, \\ \xi_i \in \mathbb{R}_+}} & \left[ \|w\|^2 + C \sum_i^n \xi_i \right] \\ \text{s.t.} & [1 - y_i(\langle w, x_i \rangle + b)] \leq \xi_i; \quad \forall i \end{aligned} \quad (10)$$

where  $C$  is a regularization/penalty parameter

Now, we have another set of inequalities that are introduced by non-negativity condition on  $\xi_i, \forall i$ . This has to be separately handled by another log barrier function.

# Soft margin SVM using log barrier method

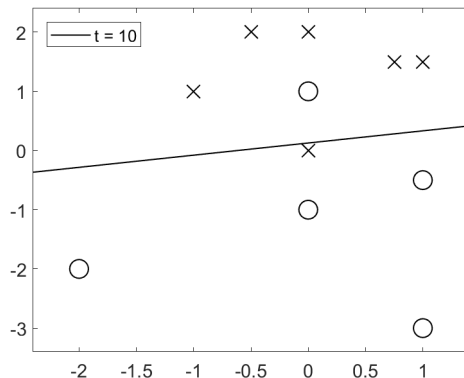
## Soft margin SVM classification (log barrier method)

$$\min_{\substack{w, b, \\ \xi_i \in \mathbb{R}_+}} \left[ \|w\|^2 + C \sum_i^n \xi_i - \frac{1}{t} \sum_i (\log(-1 + y_i(\langle w, x_i \rangle + b) + \xi_i) + \log(\xi_i)) \right] \quad (11)$$

where  $C$  is a regularization/penalty parameter

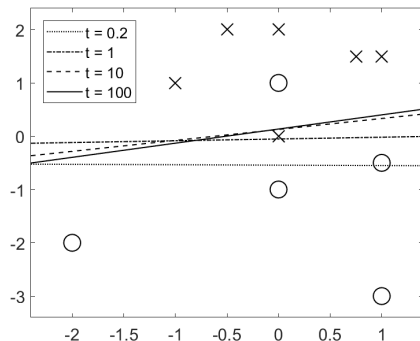
Optimization problem for finding the feasible starting point remains the same. Only the minimum value of  $s$  turns out to be negative for linearly inseparable dataset. This can be handled by appropriately choosing the initial values of  $\xi_i \forall i$ .

# Result



**Figure 11:** Separating hyperplane for a linearly inseparable data using log barrier method ( $t = 10$ ;  $C = 1$ )

# Result

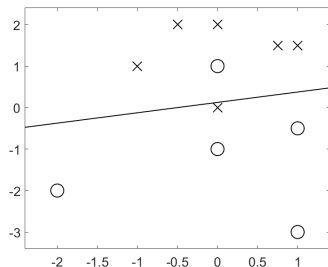


**Figure 12:** Separating hyperplane for a linearly inseparable data using log barrier method ( $t = 0.2, 1, 10, 100$ ;  $C = 1$ ) by incorporating the concept of central path [ **Remark:** Central path method ultimately converges to exact method solution if the step size for  $t$  is adequate ]

# Comparison

## Exact method

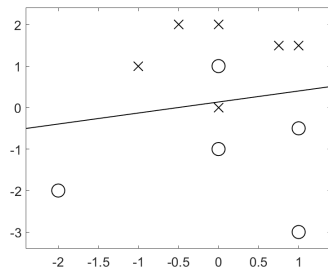
$$\begin{bmatrix} -0.2222 & 0.8889 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} - 0.1111 = 0$$



**Figure 13:** SVM using exact method

## Log barrier method

$$\begin{bmatrix} -0.2364 & 0.8889 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} - 0.1199 = 0$$



**Figure 14:** SVM using log barrier method and central path ( $t = 100$ )

- ▶ Kernel operators
- ▶ Dual optimization problem

# References



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